

## NEW 2 axis Stage Controller

ASC-02



- Application Systems
- Machine Vision
- Manual Positions
- Motion Control Products**
- Optical & Mirror Holder
- FA Parts
- Measurement & Control
- FA Electrical Parts
- Tool & Measure
- Cleanroom & AntiStatic
- Index
- Piezo Stage
- Precision Linear MS
- High Speed MS
- Motorized Goniometer
- Motorized Rotation
- Multiaxis Motorized
- Industrial Robot
- Controller & Driver & Cable**
- Custom-Built MS

### A 2 axis stage controller with built-in 5-phase stepping motor driver.

- External control with RS232C interface, manual operation and programmed operation with a dedicated controller (SJ-02).



#### Guide

- ▶ Sample programs are available for download on our website.
  - SGCommander 32/64-bit version for Windows® (only for RS232C)
  - LabVIEW for RS232C (for v.5.1/v.6i/v.7.1/v.8.6/v.2010)

#### Attention

- ▶ Power supply is DC+24V 2A.  
You need to purchase the PAT-001-POW1 (AC adapter) or prepare an adapter separately.

Part Name	Part Number
2 axis Stage Controller	<b>ASC-02</b>
Joystick Terminal	<b>SJ-02</b>
AC Adapter	<b>ASC-PS</b>

#### Primary Functions

Controller Function	○
Number of Control Axes	2
Stored Program Control	△
Feedback Control	—
Circular Interpolation Control	—
Linear Interpolation Control	—
Driver Function	Standard
Micro-step (Max. Division)	2 (half step only)
Driving Current (A/phase)	0.3 – 0.8

△...Programs can be controlled using SJT-02.

#### General Specifications

Power Voltage	DC24V 2A
Power Consumption	48VA
Operating Temperature	5 – 40°C
Storage Temperature	-20 – 60°C
Ambient Humidity	20 – 80%RH
External Dimensions (W×H×Dmm)	180×40×125
Weight (kg)	0.7

#### Interface

GP-IB	—
RS232C	○
USB	—
Ethernet	—

#### Optional

SJ-200A	—
SJ-300	—
SJ-400	—
SJ-02	○

#### Performance Specifications

Coordinate Indication Range	—
Max. Travel to Set	16,777,214
Max. Driving Speed (pps)	20,000
Min. Driving Speed (pps)	1
Acceleration/Deceleration Time (ms)	0 – 1,000

#### I/O Specification

Origin Sensor	○
Proximity Sensor	○
CW (+) Limit	○
CCW (-) Limit	○
General Purpose Input	—
General Purpose Output	—
Control Input	—
Control Output	—
Trigger Output	—

#### Control Command

Machine Origin Return	○
Theoretical Origin Setting	○
Relative Position Drive	○
Absolute Position Drive	—
Jog Operation	○
Position Appointment	—
Circular Interpolation Control	—
Linear Interpolation Control	—
Drive	○
Deceleration Stop	○
Emergency Stop	○
Speed Setting	○
Motor Free/Hold	○
Port Input	—
Port Output	—

### ASC-02 System Chart

